

Diode Rectification $AC \rightarrow DC$

Diodes used in rectifiers

- also in light detector circuits (LDR) — R increases as it gets dark
- also L.E.D.s to emit light



* normally get a resistor in series with diode to protect it from current that is too large.

MAGNETISM: lodestone, magnetite is naturally magnetised

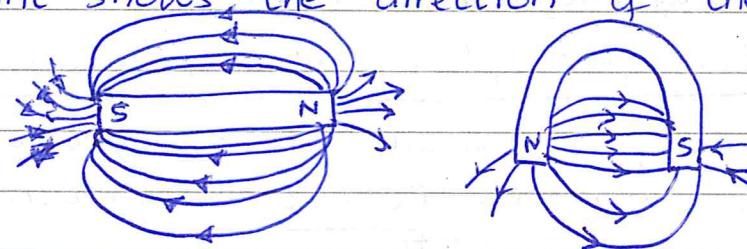
Ferromagnetic materials are attracted to magnets (e.g. iron) (nickel, cobalt).

A magnet magnetises ferromagnetic materials when they are close (e.g. pins)

A magnetic field: space around a magnet or any region of space where magnetic force can be felt.

DIRECTION of magnetic field = direction of the force a North pole would experience at that point. \Rightarrow plotting compass

Magnetic Field Line: Line drawn so that the tangent to it at any point shows the direction of the magnetic field at that point.



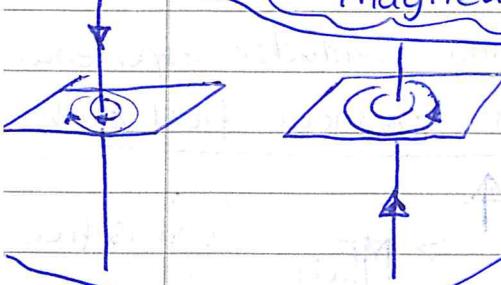
can use iron filings or plotting compasses

In 1819 Hans C. Oersted discovered that a current carrying wire has a magnetic field around it \rightarrow only when current flows. DEMO!

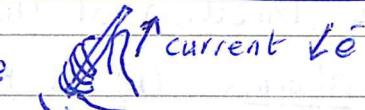
Needle deflects whenever current changes value (direction)

* EVERY Current Carrying Conductor has a

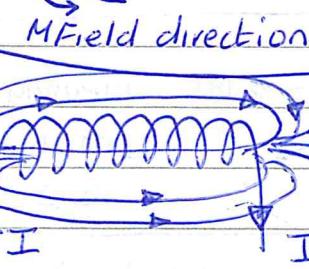
magnetic field around it caused by current



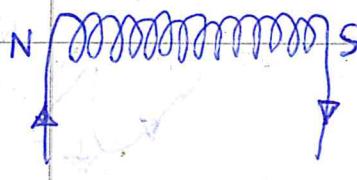
Right hand grip rule



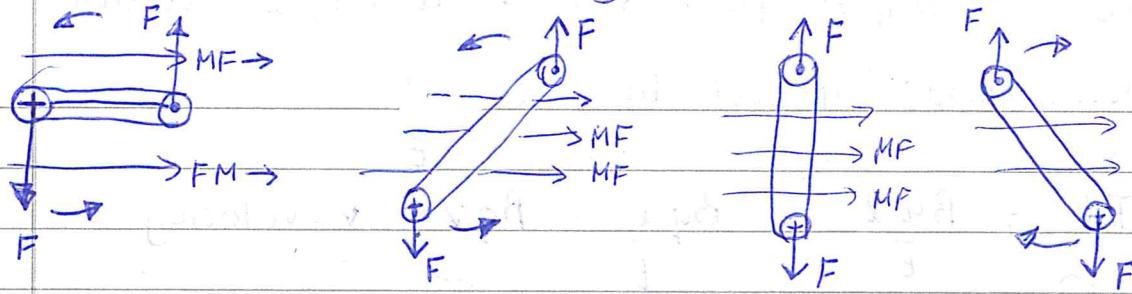
look into loop. If I moves
clkwise your end is south



solenoid (coil whose length is much longer than radius)



As the coil rotates the turning moment on it changes



So the coil would just go clockwise to 90° and if it goes beyond the moment of the couple will swing it back so it stays at 90° - UNLESS we reverse the current just as it passes 90° . Then it will continue around till it is next vertical - again we would need to reverse the direction to keep it moving.

This is the principle of the DC motor.

Force on conductor $F = BIL$ (for I at right angles to M.Field)

$F = B \cos \theta \cdot IL$ or $F = BIL \cos \theta$ (for I at angle of θ° to M.Field)
(MF @ angle θ° to I)

B = Magnetic Flux Density (VECTOR)

B depends on the strength of magnetic field. B large if Field large.

$B = \frac{F}{IL}$ = vector whose magnitude is = force that would be experienced by a conductor of length 1m carrying a current of 1Amp at right angles to the M.field at that point. The direction of B = direction of the force on a North Pole at that point. (Unit of B = Tesla (T))

1 Tesla = magnetic flux density at a point if a conductor of length 1m carrying a current of 1Amp experiences a force of 1N when placed \perp to the magnetic field

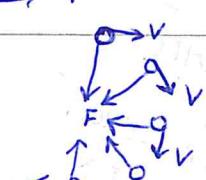
* Moving charges cause the magnetic field So even if there was no conductor but there were moving charges there would still be a force experienced by them in a magnetic force field.

Beam of

electrons will experience a force if placed in a magnetic field



Proton has force @ \perp to its direction. This changes its direction. force is always at right angles to its direction \Rightarrow it is forced round in a circle.



Same applies for electron but opp direction

ELECTROMAGNETIC INDUCTION: A changing M. Field in a coil causes an E.M.F. to be induced in the coil. Only if MField is changing!

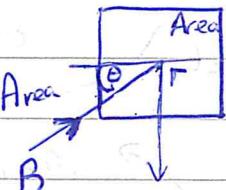
$B = \text{Magnetic flux density} = \frac{\text{measure of strength of MF, measure of no. of field lines}}{\text{per unit area}} = B$

$\phi = \text{Magnetic Flux}$

$\frac{\phi}{A} = B$, $\phi = BA$ (no of flux lines in a given area) $\phi = BA$

* For $B \perp A$ Flux Units of $\phi = T m^2 = \text{Weber}$

NB: If $\phi = BA \sin \theta$ where B is at angle θ to Area



1 Weber = flux through area of $1m^2$ of magnetic flux density 1 T

B is NOT \perp Area

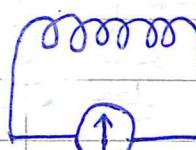
FARADAY's law of EM induction:

Size of induced EMF \propto rate of change of flux

$$E \propto \frac{d\phi}{dt}; E = N \frac{d\phi}{dt}$$

$N = \text{no. of turns on coil}$

To demonstrate Faraday's law of EM Induction:



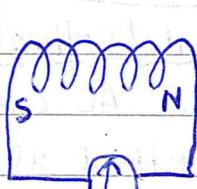
$[N \quad S]$

vary how quickly you move magnet in and out of coil

Moving magnet quicker makes bigger deflection on galvanometer showing that if the flux changes faster, the current/EMF induced is bigger.

LENZ's law: The direction of the induced EMF/ current is ALWAYS such that it opposes the change that caused it.

LENZ'S LAW



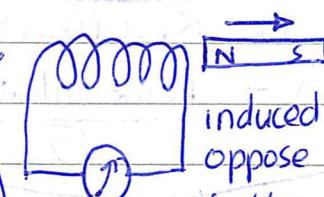
$[N \quad S]$

induced EMF tries to oppose the movement of the magnet

So R.H.S. becomes a N pole to

try to repel the magnet

Could also move coil to keep magnet still



induced EMF tries to oppose the movement of the magnet so

R.H.S. becomes a S pole to try to prevent movement of magnet by attracting it

LENZ's law follows from the principle of Conservation of Energy

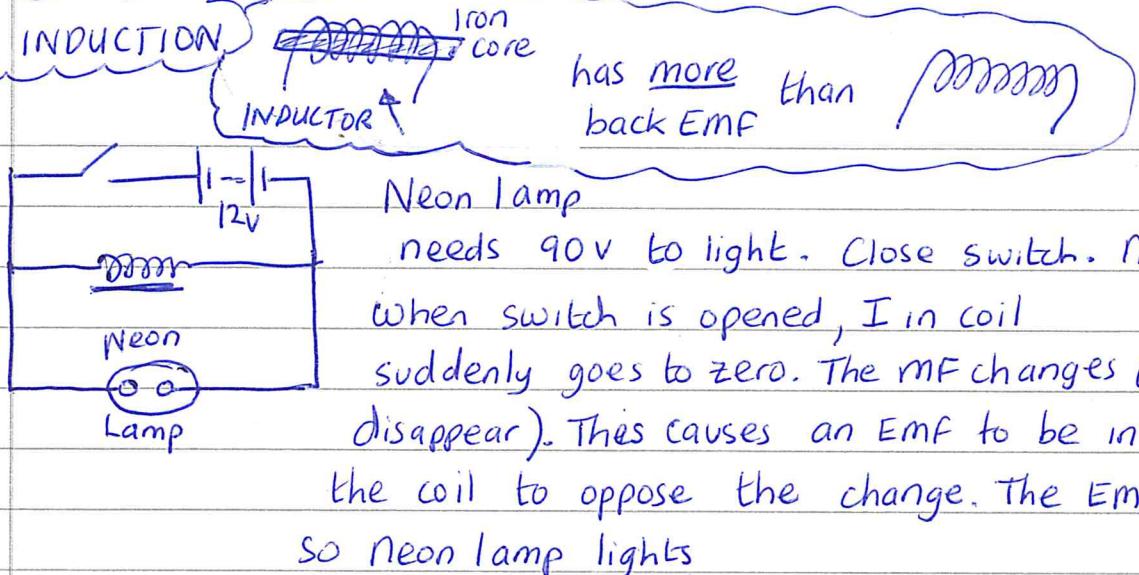
Alternator in a car is turned by the engine and that turns a magnet inside some coils of wire. The changing MFlux causes an EMF/current to be induced in the coil \rightarrow this is used to provide AC electricity to the electrical system

E-Magnetic Induction = principle

on which the electric generator is based. Cause a coil to move/rotate in a M Field and a current is induced in it \rightarrow AC electricity is generated!*

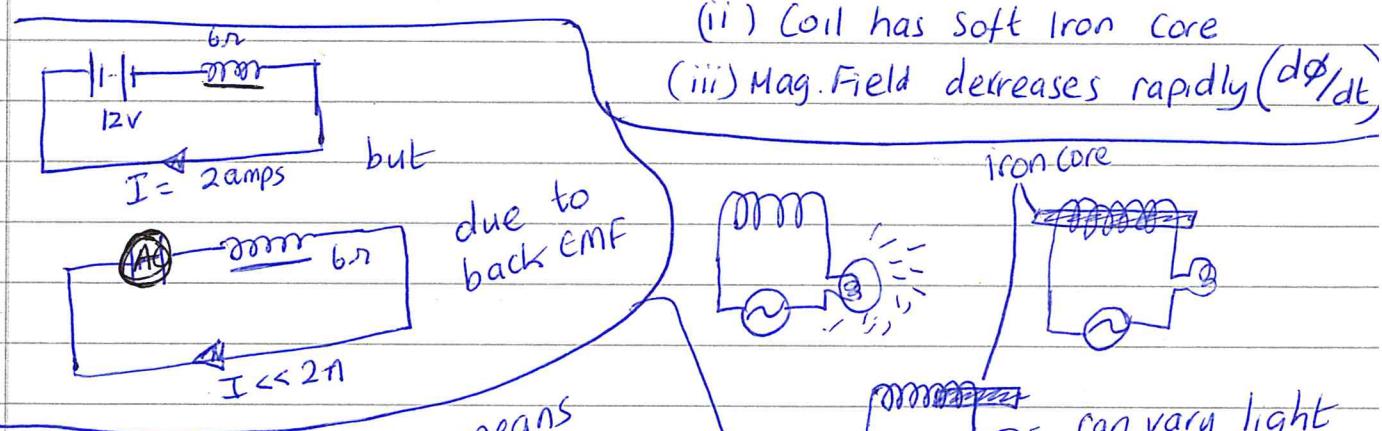
DYNAMO on bike-wheel turns magnet round coils - induces a current

SELF INDUCTION



The reason the EMF is so large = (i) Large no of turns on coil (N)

- (ii) Coil has soft iron core
- (iii) Mag. Field decreases rapidly ($\frac{d\phi}{dt}$)



Changing frequency of AC means

$\frac{d\text{flux}}{dt}$ ($\frac{d\phi}{dt}$) changes. A higher freq means greater rate of change of flux \Rightarrow greater self induction \Rightarrow greater 'resistance'

Inductor (coil) opposes flow of DC with its ohmic resistance

AC and Inductors: Inductor opposes flow of AC with ohmic Resistance
so resistance

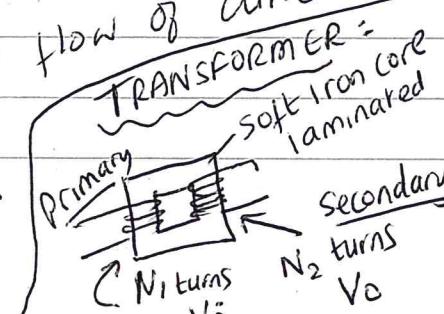
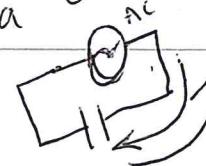
of inductor is greater when AC source connected.

Inductor \rightarrow used as a dimmer switch, supplies tuning circuits to tune to different frequencies

Inductor and AC: A charged capacitor blocks DC current

Capacitors only flows until $V_{\text{capacitor}} = V_{\text{power supply}}$, varies from one direction to the other, there is a constant flow of current in a circuit with a

Because, there is a capacitor



$$\frac{V_i}{V_o} = \frac{N_p}{N_s}$$

If there are no losses $V_i I_p = V_o I_s$